#### Fault Trees

- Fault Trees
  - dual of Reliability Block Diagram
  - logic failure diagram
  - think in terms of logic where
    - 0 = operating, 1 = failed
- AND Gate
  - all inputs must fail for the gate to fail
- OR Gate
  - any input failure causes the gate to fail
- k-of-n Gate
  - k or more input failures cause gate to fail

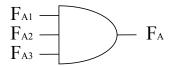
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# e.g. Triplex Bus Guardian

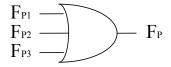
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- Active mode
  - M<sub>1</sub> and M<sub>2</sub> and M<sub>3</sub> fail =>
  - AND

Gate



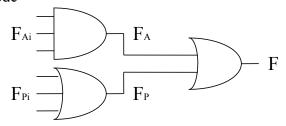
- Passive Mode
  - "cutoff" with any single unit failure =>
  - OR Gate



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# e.g. Triplex Bus Guardian

- Total Failure
  - caused by either active or passive mode



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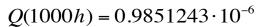
# e.g. Triplex Bus Guardian

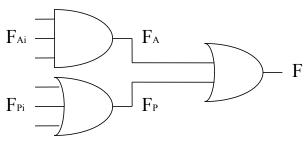
How can one use the fault tree effectively to isolate those parts of the system that need reliability considerations?

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## e.g. Triplex Bus Guardian

Combined fault model





 $Q(1000h) = 0.295545 \cdot 10^{-1}$ 

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## **Examples**

- Simple Passive TMR (no diagnosis)
  - RBD = (2 of 3): 2 operable => System operable
  - F-Tree = (2 of 3): 2 failed => System failed
- Simple TMR with Benign failures
  - RBD = (1 of 3): 1 operable => System operable
  - F-Tree = (3 of 3): 3 failed => System failed
- Summary
  - Parallel => AND
  - Series => OR
  - K-of-N => (n-k+1 of n)

#### **SHARPE**

- SYMBOLIC HIERARCHICAL AUTOMATED RELIABILITY AND PERFORMANCE EVALUATOR
- SHARPE provides a specification language and analysis algorithms for the following model types:
  - reliability block diagrams
  - fault trees
  - reliability graphs
  - series-parallel acyclic directed graphs
  - product-form queuing networks
  - Markov and semi-Markov chains
  - generalized stochastic Petri nets

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## Analysis using SHARPE

- we will be using Mobius this year, but here is a glimpse into what SHARPE looks like.
- SHARPE and SPNP are available to us with a license from Duke University, if anybody is interested.
- Below are three different SHARPE programs and output. The first two examples don't show all the details of the programs.

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## Bus Guardian (Active)

- \* SYSTEM: TRIPLEX BUS GUARDIAN -- ACTIVE FAILURE MODE
- \* MODEL: RELIABILITY BLOCK DIAGRAM
- \* -- Model Definition: block name, components, connectivity --

\*

```
block bus_gd_act
comp z exp(lamact)
parallel z3 z z z
end
```

\* Bind Values to Variable Names

\*

bind lamact 1.0\*10^-5 end \* -- Calculate CDF for System Failure \*
cdf(bus\_gd\_act)

\* -- Evaluate CDF at Specified Points

eval(bus\_gd\_act) 9 11 1 eval(bus\_gd\_act) 90 110 10 eval(bus\_gd\_act) 900 1100 100

end

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Page: 9

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## Bus Guardian (Active)

CDF for system bus\_gd\_act:

```
1.0000e+00 t( 0) exp( 0.0000e+00 t)
```

+ -3.0000e+00 t( 0) exp(-1.0000e-05 t)

+ 3.0000e+00 t( 0) exp(-2.0000e-05 t)

+ -1.0000e+00 t( 0) exp(-3.0000e-05 t)

mean: 1.8333e+05 variance: 1.3611e+10

system bus gd act

system bus\_gd\_act t F(t)

9.0000 e+00 0.0000 e+00 1.0000 e+01 0.0000 e+00 1.1000 e+01 0.0000 e+00 system bus\_gd\_act t F(t)

9.0000 e+01 0.0000 e+00

1.0000 e+02 0.0000 e+00 1.1000 e+02 1.3288 e-09

system bus\_gd\_act
t F(t)

9.0000 e+02 7.1923 e-07 1.0000 e+03 9.8512 e-07

1.1000 e+03 1.3092 e-06

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#### Bus Guardian (Passive)

- \* SYSTEM: TRIPLEX BUS GUARDIAN -- PASSIVE FAILURE MODE
- \* MODEL: RELIABILITY BLOCK DIAGRAM
- \* -- Model Definition: block name, components, connectivity --

\*

```
block bus_gd_pas
comp z exp(lampas)
series z3 z z z
end
```

\* -- Bind Values to Variable Names --

\*

bind lampas 1.0\*10^-5 end \* -- Calculate CDF for System Failure --

```
cdf(bus_gd_pas)
```

\* -- Evaluate CDF at Specified Points --

\*

```
eval(bus_gd_pas) 1 5 2
eval(bus_gd_pas) 10 50 20
eval(bus_gd_pas) 100 500 200
```

end

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Page: 11

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## Bus Guardian (Passive)

CDF for system bus\_gd\_pas:

```
1.0000e+00 t( 0) exp(0.0000e+00 t)
+ -1.0000e+00 t( 0) exp(-3.0000e-05 t)
```

mean: 3.3333e+04 variance: 1.1111e+09

\_\_\_\_\_

system bus\_gd\_pas t F(t)

1.0000 e+00 3.0000 e-05 3.0000 e+00 8.9996 e-05 5.0000 e+00 1.4999 e-04 system bus\_gd\_pas
t F(t)

1.0000 e+01 2.9996 e-04 3.0000 e+01 8.9960 e-04 5.0000 e+01 1.4989 e-03

system bus\_gd\_pas t F(t)

1.0000 e+02 2.9955 e-03 3.0000 e+02 8.9596 e-03 5.0000 e+02 1.4888 e-02

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Page: 12

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#### SYSTEM: TRIPLEX BUS GUARDIAN -- ACTIVE FAILURE MODE MODEL: RELIABILITY BLOCK DIAGRAM

block bus\_gd\_act comp z exp(lamact) parallel z3 z z z end

block bus\_gd\_act3 comp z exp(lamact3) end

bind lamact 1.0\*10^-5 lamact3 1/(1.8333\*10^5) end

cdf(bus\_gd\_act)
cdf(bus\_gd\_act3)

eval(bus\_gd\_act) 900 1100 100 eval(bus\_gd\_act3) 900 1100 100

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This is the RBD defined as 3 parallel modules

Now I pretend this is the same as using 1/MTTF (calculated for a parallel system) in a simple 1 module expression.

Bind Values to Variable Names

Calculate CDF for System Failure

Evaluate CDF at Specified Points. Even though the MTTF are the same, the CDFs are different.

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#### CDF for system bus\_gd\_act:

1.0000e+00 t( 0) exp(0.0000e+00 t) + -3.0000e+00 t( 0) exp(-1.0000e-05 t) + 3.0000e+00 t( 0) exp(-2.0000e-05 t) + -1.0000e+00 t( 0) exp(-3.0000e-05 t)

mean: 1.8333e+05 variance: 1.3611e+10

\_\_\_\_\_

CDF for system bus\_gd\_act3:

1.0000e+00 t( 0) exp( 0.0000e+00 t) + -1.0000e+00 t( 0) exp(-5.4546e-06 t)

mean: 1.8333e+05 variance: 3.3610e+10 9.0000 e+02 7.1923 e-07 1.0000 e+03 9.8512 e-07 1.1000 e+03 1.3092 e-06

\_\_\_\_\_

system bus\_gd\_act3 t F(t)

9.0000 e+02 4.8971 e-03 1.0000 e+03 5.4398 e-03 1.1000 e+03 5.9821 e-03

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Page: 14

Page: 13